Compact n-gram models by incremental growing and clustering of histories

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Abstract

This work concerns building n-gram language models that are suitable for large vocabulary speech recognition in devices that have a restricted amount of memory and space available. Our target language is Finnish, and in order to evade the problems of its rich morphology, we use sub-unit words, morphs, as model units instead of the words. In the proposed model we apply incremental growing and clustering of the morph n-gram histories. By selecting the histories using maximum a posteriori estimation, and clustering them with information radius measure, we obtain a clustered varigram model. We show that for restricted model sizes this model gives better cross-entropy and speech recognition results than the conventional n-gram models, and also better recognition results than non-cluster varigram models built with another recently introduced method.

Index Terms: language models, clustering, information radius, speech recognition

1. Introduction

Statistical language models try to determine the probability distribution \( P(S) \) over text strings \( S \), which are usually observed as sequences of words, \( w_1 \ldots w_n = w^n_0 \). They are a vital part of e.g. speech recognition systems. A large number of statistical language models have been developed and studied, but the most widely used models are still the n-gram models, based on the assumption that the probability of a word depends only on the \( n-1 \) previous words. When an n-gram model is trained, all different n-grams up to length \( n \) are collected from the selected training corpus, and probability for each \( n \)-gram is estimated by the ratio of occurrences of the \( n \)-gram \( w_{i-n+1}^i \) and its history \( w_{i-n+1}^{i-1} \). Estimates are then smoothed, giving some probability mass to unseen events, which are then estimated by the distribution of shorter n-grams. However, the number of different n-grams in a large corpus can be very high, and also the sizes of the n-gram models easily grow impractically large. The problem is that on-line speech recognition requires models that it fit well into the work memory of the used device. We can well assume that the variety of devices will grow to include also personal digital assistants and mobile phones. Thus the resources will be limited also in the future, regardless of their overall growth.

Trivial ways of building smaller n-gram models are to restrict either the training data or the maximum n-gram length. However, it is clear that neither of those will get us a good model. Pruning, i.e. removing some of the n-grams from a full n-gram model, is a better way of reducing the model size. One efficient pruning method is entropy-based pruning [1]. There relative entropy resulting from removing each single n-gram from the model is calculated, and those n-grams that increase the entropy least are pruned. There are also ways of getting a pruned model without first estimating the full model. E.g. Siivola and Pellom [2] show a way of building the model incrementally from a unigram model by adding suitable sets of n-grams at a time. The result is so called varigram model, where there is no preset limit for the lengths of the n-grams included in the model. Thus the longer contexts are used only there where they are really needed.

Another common approach to the data sparseness problem is clustering. Traditionally, clustering has been added into n-gram models by the means of clustering the model units, i.e. words. The basic class-based n-gram model was presented in [3], often referred as IBM model. Some extensions for the model has been reported to work significantly better, see e.g. [4]. In addition to the benefit of saving space and memory, one can hope that the decrease in the number of parameters helps to avoid overlearning.

Even if pruning and clustering are in use, applying standard n-gram models to languages that are highly-inflecting or compoundable to cluster some larger entities. A logical things to cluster in our case is to model smaller segments of text instead of words. A good choice for the segments is to be morpheme-like segments found statistically. E.g. for Finnish, utilization of morphs found by the Morfessor algorithm [5] has improved direct prediction performance compared to words, and reduced error rates in large vocabulary speech recognition compared to either words or grammatical morphs [6]. Statistical morphs have also been tested in Turkish and Estonian speech recognition with similar results [7].

For finding a desired balance between the model size and accuracy, we propose a method that makes use of the morph based language modeling, and combines both pruning and clustering. The main issue is applying clustering to a morph-based model. When we use morphs, the number of model units can be very limited. The benefit of clustering an already small number of units, at least into hard clusters, is not very compelling. Instead it is more sensible to cluster some larger entities. A logical things to cluster in n-gram models are the histories of the n-grams, i.e. the sequences that are used predict the next model unit. For each history cluster we can then estimate a collective prediction distribution. The histories that we cluster are selected by the means of incremental building of the model.

1.1. Related work

Several approaches for building varigram models have been presented. We already mentioned a recent one [2]. Naturally, also various methods for clustering the model units have been developed. Some, such as Niesler and Woodland [8], even combine
varigram models and clustering. However, there is not much research done on models where n-gram histories would be clustered into equivalence classes in a similar manner that we will do. Goodman [9] mentions the idea in the section of his survey that concerns clustering, but solely states that there are many difficult issues to solve in it.

The closest related method that we are aware of is presented by Siu and Ostendorf [10]. They used clustering of n-gram histories in order to handle conversational speech characteristics such as filler words and repetitions. The search algorithm compares each history only to ones that are a small variation of its context, which is more limited than our approach. They reported that they could use a considerable smaller models in order to get the same perplexity and speech recognition results as for standard n-gram models. However, most of the benefit was due to using a varigram model instead of a full n-gram model.

Another exception is the work by Xu and Jelinek [11], where randomly grown Decision Trees were used to cluster word histories. Their language model outperformed traditional n-gram model in both perplexity evaluation and speech recognition.

2. An n-gram model of clustered histories

Let us denote the units of the model as \( w_i \) and each included history as \( h_j \), \( j \in \{1, \ldots, N\} \). We try to find a set of clusters of histories \( c_k \), \( k \in \{1, \ldots, C\} \), so that each history belongs to one cluster. In addition, we assume that the next unit depends only on the cluster of the history, not on the history itself. When predicting the next unit \( w \) for the known history \( h \), we get

\[
P(w \mid h) = P(w \mid c(h)),
\]

where \( c(h) \) denotes the cluster of the history \( h \).

For this kind of model to work in practice, those histories that belong to the same cluster should have as similar prediction distributions as possible. There are several possible measures to compare the similarity of the distributions. We use information radius, which is a bounded metric, and reported to work well on auto-induction of semantic classes [12]. Information radius between distributions \( p \) and \( q \) is

\[
IRad(p \parallel q) = D(p \parallel \frac{p+q}{2}) + D(q \parallel \frac{p+q}{2}),
\]

where \( D(x \parallel y) \) is the Kullback-Leibler divergence of the distributions.

2.1. MAP estimation of the model

In a general level, conventional n-gram models are based on maximum likelihood (ML) estimates. I.e., they try to find a model \( G_{ML} \) that maximizes the likelihood of the observed data \( O \):

\[
G_{ML} = \arg \max_G P(O \mid G)
\]

The \( P(O \mid G) \) is just the likelihood of the training data according to the model:

\[
P(O \mid G) = \prod_i P(w_i \mid h_i, G),
\]

where \( (w_i, h_i) \) are the n-grams in \( O \). When we maximize the likelihood \( P(O \mid G) \) we minimize the coding length \( L \) of the data given the model, as known from the information theory. But this should not be what we really want: If the model is flexible enough, it will overlearn the training data, and not generalize beyond it.

Instead of \( P(O \mid G) \), we should be more interested in finding the model \( G_{MAP} \) that is the most probable when we know the data. Applying Bayes’ theorem, we get

\[
G_{MAP} = \arg \max_G P(G \mid O) = \arg \max_G \frac{P(G)P(O \mid G)}{P(O)}.
\]

This estimate is called maximum a posteriori (MAP) estimate. Note that the probability of the data \( P(O) \) is not affected by \( G \).

With a suitable prior probability \( P(G) \), MAP estimation has a direct connection to the Minimum Description Length (MDL) principle, which is used e.g. in [2] to decide which n-grams are added to the language model. An introduction to the connection between Bayesian and MDL frameworks is found e.g. in [13].

2.2. Search algorithm

The components of our model were the n-gram histories, and \( C \) clusters \( c_k \) together with emission distributions \( P(w_i \mid c_k) \). Each history has a link to the cluster to which it belongs. The basic algorithm for constructing the model \( G \) is the following:

1. Set \( n = 1 \)

2. For each n-gram history \( w_{i-n+1} \) (or empty history if \( n = 1 \)) in the training data \( O \):
   a. If \( n > 2 \) and neither of the \((n-1)\)-gram histories \( w_{i-n+2} \) or \( w_{i-n+1} \) are in the model, skip the history.
   b. Select the cluster \( c_k \) in the model that minimizes the information radius between ML estimates of \( P(w_i \mid c_k) \) and \( P(w_i \mid w_{i-n+1}) \).
   c. Calculate \( \Delta \log P(G \mid O) = \Delta \log P(G) + \Delta \log P(O \mid G) \) for the cases where (1) \( w_{i-n+1} \) is added to the model into the cluster \( c_k \), and (2) a new cluster containing \( w_{i-n+1} \) is added to the model.
   d. Do (1) or (2) depending on which increases the posterior probability \( P(G \mid O) \) more. If neither does, skip the history.

3. If new histories were added into the model, increase \( n \) by one and go to 2. Otherwise stop.

We use information radius to select the best matching cluster instead of calculating the change in posterior probability mostly because it is computationally more efficient. The search can be optimized more by first testing that the most probable units that follow the cluster and the new history are similar.

The idea behind the step 2a. is to speed up the training even more. Calculating prediction distributions and searching for nearest clusters cannot be done to every n-gram of the training data, at least if we want \( n \) to be large. Instead we grow those n-grams that are already accepted in the model. Thus we assume that if some history was considered useful in predictions, longer histories that include it may also be useful.

2.3. Model priors

Next we need the prior probabilities of the model, \( P(G) \). We assume a predefined lexicon of model units. In the model we save \( N \) histories from the training data and the units of which they consist
of. Then we have \( C \) clusters, and save the cluster of each history. Moreover, each cluster has a prediction distribution for a number of units. Each saved parameter has a prior distribution (or a coding scheme, if we use the MDL framework). Prior probability of the model is the product of all priors of the parameters.

Our goals in the selection of the priors were very simple: First, give smaller probabilities to models that have larger number of histories. Second, give smaller probabilities for clusters whose distributions contain a wide range of morphs (and thus consume much memory). Otherwise, give equal probabilities to all possibilities.

Thus the more histories and clusters there will be in the model, the smaller \( P(G) \) will be. On the other hand, \( P(O | G) \) will be larger, so a compromise between the size and the accuracy of the model is made. Since we are not actually interested in finding the optimal coding for the training data, we can also weight the two parts by selecting some constant \( \alpha \) and setting \( P(G | O) \) proportional to \( P(G)^{\alpha} P(O | G) \). This serves as a practical way to get larger or smaller models without redesigning the prior.

3. Experiments

In our experiments we compared three kind of language models: Baseline n-gram models built with the SRI toolkit [14], varigram models built with the growing algorithm [2], and the proposed clustered varigram models. First we calculated cross-entropy for held-out data sets, and then used the models in a speech recognition system.

Our main Finnish text corpora are from the language bank of Finnish IT center for science (CSC)\(^1\). For the training material we selected several books and magazines, total 8 600 000 words. A morph lexicon of 2 113 units was estimated from it using the Morfessor software \([5]\). We also trained some growing varigram models with the full 150 million word data for comparison, still using the same set of morphs.

Cross-entropy calculates the average number of bits needed to encode one data unit (morph) using the model, and is logarithm of the more commonly used measure, perplexity\(^2\). However, decrease in cross-entropy may generally reflect more accurately the potential decrease in error rate in speech recognition \([9]\). For cross-entropy test we had two separate corpora: First consisted of articles of one year of the tabloid magazine Italehti (100 000 words). Second was a book (50 000 words) that was used also in speech recognition tests.

For speech recognition experiments we used the speech recognition system of the Adaptive Informatics Research Centre (AIRC) \([7]\). The book in audio form contained 13h of speech read by one female speaker \([6]\). Acoustic models were trained for the speaker using the first 11 hours. Speech recognition results were measured by word error rate, i.e. the percentage of words not recognized properly from the test set.

3.1. Cross-entropy results

For cross-entropy evaluation we built up baseline 1-gram, 2-gram and 3-gram models, and several growing varigram and clustered

\[P(G) = \frac{1}{C} \sum_{i=1}^{C} p(G|H) p(H)\]

varigram models of different sizes. Our area of interest in the language model sizes was from 200 000 to one million parameters. For the both varigram types, the size could be varied by adjusting the weight parameter, whereas size of the baseline models could not be adjusted more than by selecting the n-gram length.

The cross-entropy results for the two tasks are plotted in Figures 1 and 2. Both varigram model types clearly win the equal sized baseline models. We also see that the clustered model is somewhat better than the non-clustered varigram model with larger models and in the harder task (tabloid magazine). In addition, using the full 150 million word training data did not help with less than million parameter models. If also the model size was allowed to grow almost 20 times larger, we reached cross-entropy 3.56 for the tabloid data and 3.81 for the book data.

3.2. Speech recognition results

For speech recognition tests we selected baseline 2-gram and 3-gram models, and three models for each varigram model types. The smallest varigram models had about 250 000 parameters, middle sized models had about 500 000 parameters and the largest models had about one million parameters.

For each individual model, recognition parameters were first

\[H = \frac{1}{n} \sum_{i=1}^{n} H_i\]

\[P(H) = \prod_{i=1}^{n} p(H_i)\]

\[P(O | G) = \frac{1}{|G|} \sum_{G \in \mathcal{G}} p(O | G) p(G)\]

\[p(O | G) = \sum_{G \in \mathcal{G}} p(O | G) p(G)\]

\[p(G) = \frac{1}{C} \sum_{i=1}^{C} p(G|H) p(H)\]

\[p(G|H) = \prod_{i=1}^{n} p(G_i|H_i)\]

\[p(H) = \prod_{i=1}^{n} p(H_i)\]

\[p(O | G) = \frac{1}{|G|} \sum_{G \in \mathcal{G}} p(O | G) p(G)\]

\[p(G) = \frac{1}{C} \sum_{i=1}^{C} p(G|H) p(H)\]

\[p(G|H) = \prod_{i=1}^{n} p(G_i|H_i)\]

\[p(H) = \prod_{i=1}^{n} p(H_i)\]
optimum. The same applies to the selection of the histories to include in the model. Every realistic algorithm, such as ours, will only find a local optimum. The same applies to the selection of the histories to include in the model.

One clear, and presumably even critical, improvement to the proposed model would be to use soft clustering instead of the hard one. That would allow smaller number of clusters but still a more flexible model, as there would be no need for exactly similar distributions among the histories. Optimizing the soft clustering is clearly even a more challenging task, but we believe that the useful methods already exist, e.g. in the field of blind source separation. How to apply the methods so that they cope with the high dimensionality of the language data is the main issue in our future research.

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6. References